SUMMER 2022 FAU ISENSE REU



CENTER FOR CONNECTED AUTONOMY AND ARTIFICIAL INTELLIGENCE

College of Engineering and Computer Science Florida Atlantic University

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BATTERY-FREE
UNDERWATER
WIRELESS
COMMUNICATION
SENSORS USING
SCATTER
COMMUNICATION
PRINCIPLES









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THE PROBLEM WITH UNDERWATER WIRELESS TODAY

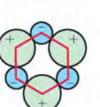




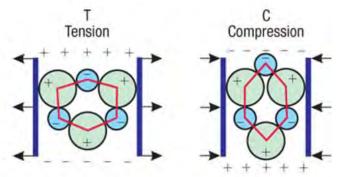


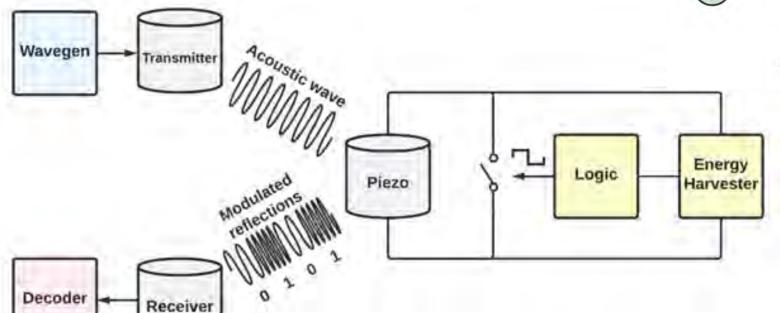
Piezoelectric Effect in Quartz

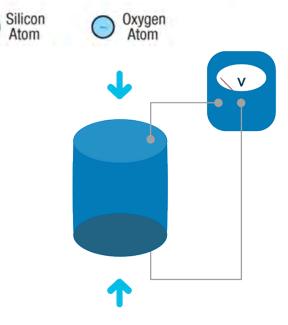
OUR SOLUTION



No Stress



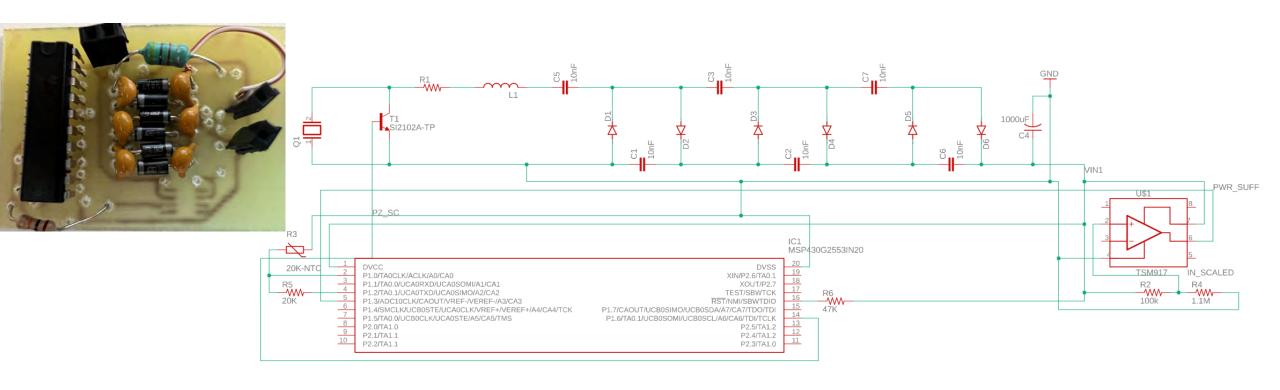


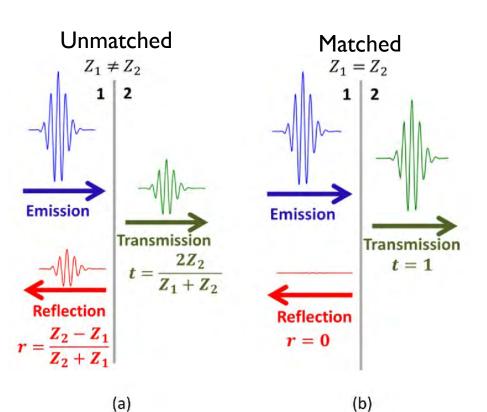






DESIGNING AND FABRICATING THE SCATTER ACOUSTIC SENSORS





Z = p/v



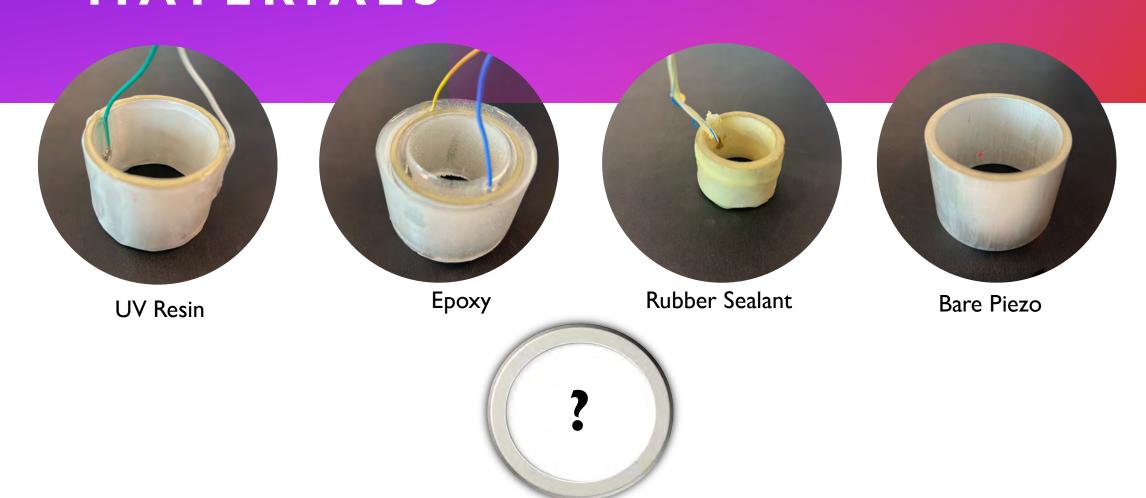


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No.	Materials	Density (kg/m³)	Sound speed (m/s)	Impedance (Rayl)
1	air	1.23	340	418
2	Water	1053	1490	1.56×10^6
3	Cork	0.24	530	1.27×10^5
4	Aluminum	2690	6420	1.73×10^7
5	Steel	7860	5950	4.64×10^7
6	PDMS	969	1119	1.08×10^6
7	PU	1528	1040	1.59×10^6
8	Ероху	1180	2490	2.95×10^6
9	Hydrogel	1000	1600	1.60×10^6
10	Ecoflex	1070	989	1.06×10^6

ACOUSTIC IMPEDANCE MATCHING

TESTING WITH DIFFERENTE MATERIALS



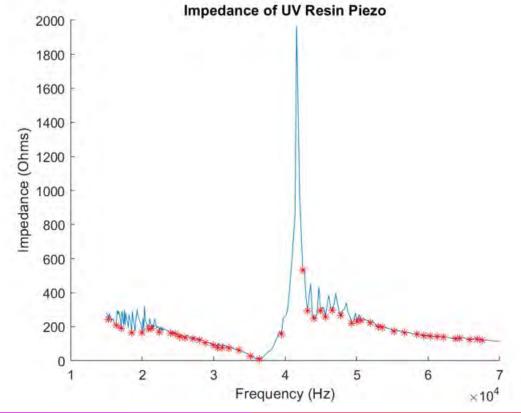
Polyurethane

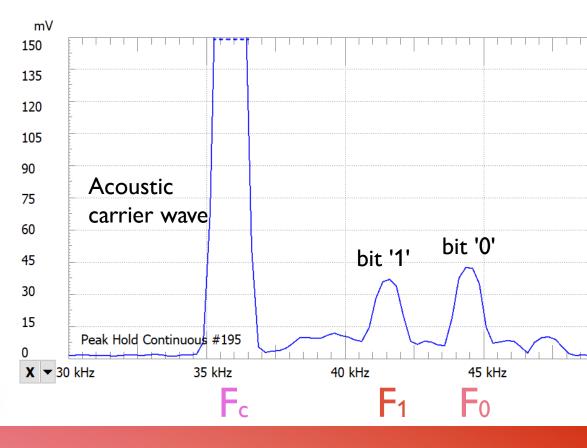




CHOOSING THE RIGHT FREQUENCIES





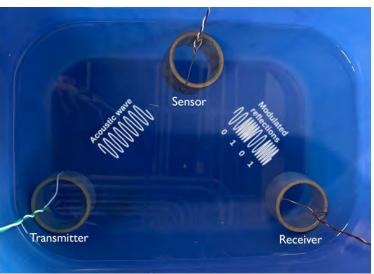


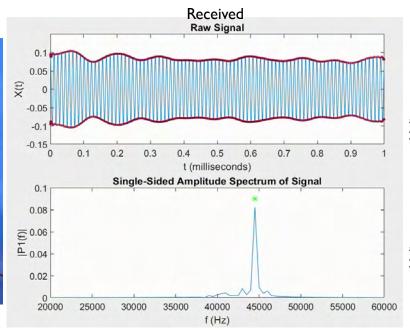


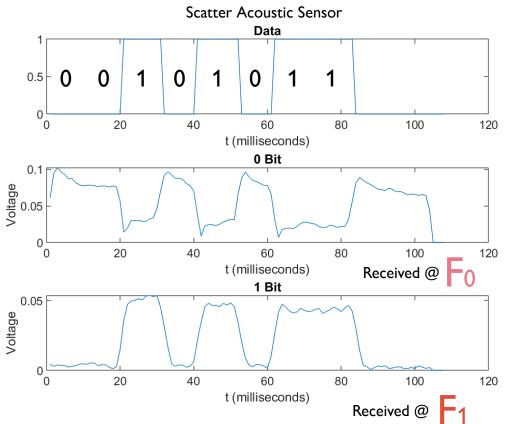


DATA DECODING FROM REFLECTIONS

Experimental setup in the lab





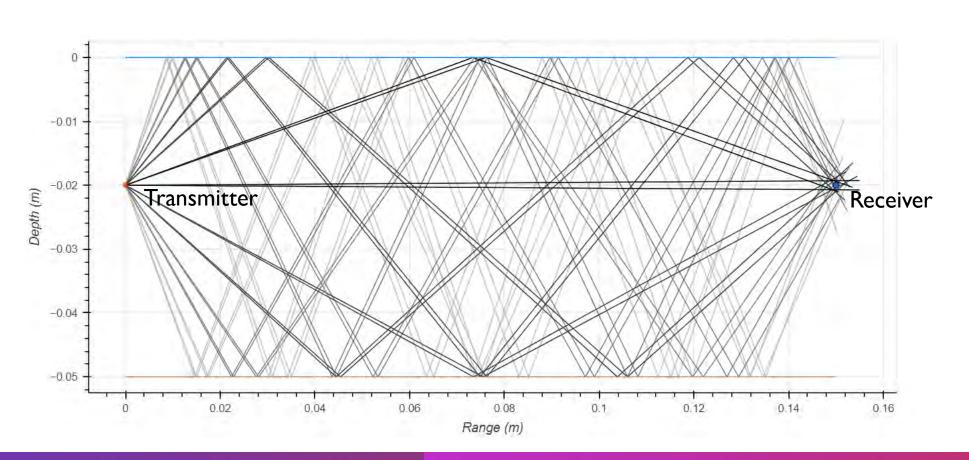


SNR >= 48dB





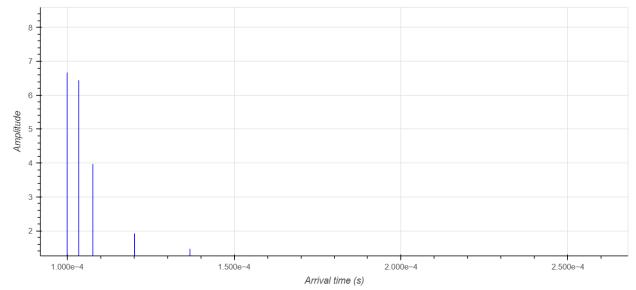
SIMULATING THE UNDERWATER CHANNEL



 Simulate underwater acoustic propagation using the popular Bellhop ray-tracing framework

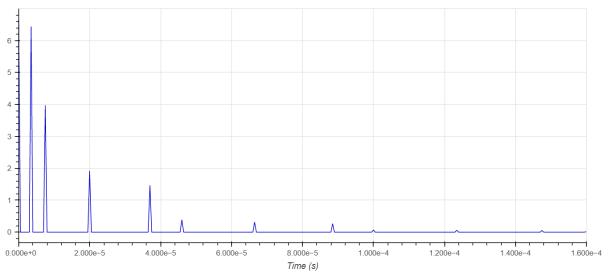
Objectives

- Test our decoder with simulation data before we apply it to field data
- "Train" our decoderwith data frommultiple environments



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- Convert arrivals to impulse response time series
- Use impulse response to simulate our received signal

- Arrival structure at the receiver
- We can look up the time-of-arrival, angle-ofarrival and number of surface/bottom bounces



EXAMPLE OF UNDERWATER ACOUSTIC CHANNEL IMPULSE RESPONSE

CONCLUSIONS AND FUTURE WORK





Conclusions

- The sensor is capable of wirelessly harvesting
 2.8V from an acoustic carrier wave of 10 V
- Data can be decoded at the receiver with no errors
- Demonstrated low-bit rates of 100 bps at small ranges 15cm

Future Objectives

- Increase the communication range and bit rate
- Test with multiple sensors
- Attempt potting with materials that offer better acoustic impedance with the water (e.g. PU)

CALL FOR PAPERS: The 19th IEEE International Conference on Mobile Ad-Hoc and Smart Systems (MASS 2022), Denver, Colorado, October 20 - 22, 2022









